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Discussion of
A Term Structure Model for Defaultable
European Sovereign Bonds
by
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Outline

- Summary of the Paper
- General Comments
- Technical Comments
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Overview

- This paper addresses the **current reality** of **possible default of sovereign bonds** by **EMU nations** by proposing an implementable framework to **assess the response** of their **yield spreads** over German bund yields **to their own, German and macroeconomic variables**
- For **Italy, Greece and Spain** – a prescient choice? – the main question addressed is “to what extent these **yield spreads** can be **attributed to economic fundamentals**” – in particular national **budget deficits** and **debt** to GDP levels – of each country in relation to those of Germany
- An **affine model** is developed to explain the **short rate** and **market prices of risk** for **sovereign bonds** of **various maturities** for the EMU nations together with Germany and adds factors in the yields – discount factors – for **losses** and **illiquidity** in the sovereign bonds of the former
- An **SVAR model** is developed to estimate the **impact on** one nation’s **spreads** and **Germany’s** corresponding **yields** for **9 maturities** up to **10 years** in terms of their **3 leading** covariance eigenvalue **factors** and macroeconomic variables – **industrial production, inflation, deficit/GDP, debt/GDP** and a **market risk indicator** – for each nation



Findings

- Factor loadings on the yield curve for the macroeconomic variables and impulse responses over 1, 5 and 10 years of the spreads to macroeconomic variable shocks are analyzed
- These accord with intuition
- **Market stress** – Moody's Baa corporate bond yield – in all three countries affects the long end of the spread curves for maturities 6 to 8 years – bearing in mind that 10 years is the maximum studied – wise?
- For **Italy** the one standard deviation shocks which have the largest impulse responses on one year maturity spreads are **market stress, Germany's debt and national debt**
- For **Spain** these are **Germany's debt, market stress and national debt** have the largest impacts
- For **Greece** these are **national debt and deficit**
- For all three countries the largest impact of national debt is on one year spreads – reflecting annual budget cycles?



General Comments

- Some of the **conclusions** drawn in the paper strike the reader as **quite obvious**
- “A possible explanation (for the importance of German debt) is a perception of markets that **Germany is the lender of last resort** (for) the largest economies in the EMU”
- The yield curve factor loading of industrial activity is always negative “suggesting that **economic growth** is perceived as **reducing sovereign risk**”
- The paper contains a **good literature survey** and **informative graphs**
- While **generally clear** and **well written** it is confusing and unclear in some places
- Some **terminology could be improved** e.g. yields are not always “paid” but mostly only realized and affine functions are referred to as “linear”
- There is a **derivation** on p.6 which appears **never** to have been **used** and perhaps the **others** on p.6 are **not needed** in specifying the affine model used
- Some **references** are **missing**



Technical Comments

- It is the use of the **exponential affine model** that actually **guarantees arbitrage free bond yields** – both risk free (German) and defaultable
- The assumption (Hypothesis 3) that the **impacts** of the **factors** and **macroeconomic variables** on **loss rates** and **illiquidity costs** are **uniform across yield maturities** is a bit heroic
- The Cochrane & Piazzzi (2008) practice of **orthogonalizing yield factors** with the **macroeconomic variables** implies that **only yield variability uncorrelated with the other variables remains** which is to my mind somewhat roundabout and **needs some explanation and justification**
- Each country / Germany SVAR model has 370 parameters with 1945 observations – approximately **5 observations per parameter!** Enough?
- In Appendix 3 “identifying “ parameter (0) restrictions are made which imply that the **structural form** of the **SVAR model** could be directly **estimated by OLS** as it is in **Wold recursive** – or cascade – **form**



Some Queries and Suggestions

- How were the **x-axes** of the impulse response diagrams **scaled**?
- Are those **several with virtually no impact** understood?
- The text should always refer in full to “**industrial activity**”
- How was the **bootstrap parameter error estimation** actually achieved?
- Rather than using **proxy monthly variables at quarterly frequency** to interpolate quarterly macroeconomic variables at monthly frequency were **other methods** for this common problem considered?
- We have had success with **deterministic scaling** [Dempster *et al.* \(2003\)](#)
- Have **alternative arbitrage –free factor evolution specifications** such as the [Christensen *et al.* \(2007\)](#) enhancement of [Nelson & Siegel \(1987\)](#) been considered?
- Have the use of **latent yield curve factors** with some form of **Kalman filtering** with **maximum likelihood** parameter estimation in the **EM algorithm** been considered? Such methods are amenable to including observed macroeconomic variables in the state variable dynamics and filtering



Are Three Factors Sufficient?

Table 1: PCA results for oil futures and interest rates

	variance explained – interest rates (%)	variance explained – oil futures (%)
first factor	95.70	93.55
second factor	4.06	5.89
third factor	0.21	0.47
fourth factor	0.02	0.07
fifth factor	0.00	0.02

Litterman & Scheinkman (1991)

The Exponential Affine Model

$$F_t(\tau) = \mathbb{E}_t^Q[\exp(\mathbf{v}_T)]$$

Future price

$$P_t(\tau) = \mathbb{E}_t^Q[\exp(-\int_t^T r_s ds)],$$

Bond price

$$\mathbf{x}_t = \phi_0 + \phi_Y' \mathbf{Y}_t,$$

Observation dynamics

$$d\mathbf{Y}_t = K(\Theta - \mathbf{Y}_t)dt + \Sigma\sqrt{\Upsilon}d\mathbf{W}_t^Q,$$

Factor dynamics

$$Z_t(\tau) = \exp[A(\tau) + B'(\tau)\mathbf{Y}_t],$$

Price dynamics



State Space Model Formulation

Transition Equation

$$Y_t = d + \Phi Y_{t-1} + \eta_t,$$

$$E[Y_t | Y_{t-1}] = d + \Phi Y_{t-1}$$

$$\text{var}(\eta_t) = \text{var}(Y_t | Y_{t-1}) = \Omega(Y_{t-1}) := \Omega_t$$

Measurement Equation

$$Z_t = A + B Y_t + \varepsilon_t$$



Measurement Error Specification

We define the new state vector X in terms of Y and ε , i.e. $X_t = \begin{pmatrix} Y_t \\ \varepsilon_t \end{pmatrix}$

and assume that ε_t follows a first order vector auto-regressive process

$$\varepsilon_t = \Pi \varepsilon_{t-1} + u_t$$

Then the **augmented state space form** becomes

$$X_t = f + GX_{t-1} + w_t$$

$$Z_t = A + CX_t,$$

Dempster & Tang (2011)



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