Posterior Means and Precisions of the Coefficients in Linear Models with Highly Collinear Regressors*

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Abstract

When there is exact collinearity between regressors, their individual coefficients are not identified, but given an informative prior their Bayesian posterior means are well defined. The case of high but not exact collinearity is more complicated but similar results follow. Just as exact collinearity causes non-identification of the parameters, high collinearity can be viewed as weak identification of the parameters, which we represent, in line with the weak instrument literature, by the correlation matrix being of full rank for a finite sample size T, but converging to a rank deficient matrix as T goes to infinity. This paper examines the asymptotic behaviour of the posterior mean and precision of the parameters of a linear regression model for both the cases of exactly and highly collinear regressors. We show that in both cases the posterior mean remains sensitive to the choice of prior means even if the sample size is sufficiently large, and that the precision rises at a slower rate than the sample size. In the highly collinear case, the posterior means converge to normally distributed random variables whose mean and variance depend on the priors for coefficients and precision. The distribution degenerates to fixed points for either exact collinearity or strong identification. The analysis also suggests a diagnostic statistic for the highly collinear case, which is illustrated with an empirical example.

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1 Introduction

This paper presents a Bayesian analysis of the multicollinearity problem for linear regression models with highly collinear regressors. Multicollinearity is an old problem in time series analysis where the regressors tend to be highly persistent. For example, Spanos and McGuirk (2002, 365-6) note that although high degree of collinearity amongst the regressors is one of the recurring themes in empirical time series research, the manifestation of the problem seems unclear; there is no generally accepted way to detect it; and there is no generally accepted way to deal with it. Pesaran (2015, Section 3.11) discusses the multicollinearity problem and shows that in the case of highly collinear regressors the outcomes of individual t-tests and associated joint F-tests could be in conflict, with statistically insignificant outcomes for the individual t-test and a statistically significant outcome for the joint test. The term "multicollinearity" originates with Ragnar Frisch (1934) as a contraction of his phrase multiple collinearity which refers to a situation in which several linear relationships hold between variables and the meaning subsequently changed to linear dependence between regressors.

The adverse effects of multicollinearity on the precision with which the parameters are estimated can be reduced by the use of extraneous information, should it be available. The extra information can take the form of either pooling data or using prior information. The prior information may be exact, for instance that a coefficient is zero or takes a particular value, or the prior information may be probabilistic, as in the Bayesian approach we focus on. The properties of Bayesian procedures are of particular interest, since other suggested solutions such as shrinkage estimators and ridge regression can be interpreted in Bayesian terms and, as Leamer (1978) notes, Bayesian estimators can be interpreted in terms of pooling two samples of data as Tobin (1950) did in combining cross-section and time-series data. Poirier (1998) provides a Bayesian treatment of nonidentified models.

One can distinguish three cases. First, when there is exact collinearity between regressors, their individual coefficients are not identified, but given an informative prior their Bayesian posterior means are well defined. Second, the correlation matrix between regressors may be ill-conditioned in small samples, but has full rank for all T, including the case where $T \to \infty$. Here a Bayesian approach can compensate for the ill conditioned correlation matrix in small samples, but the posterior means converge to the true values in large samples, so for large samples there is little to choose between Bayesian and frequentist approaches. We consider the Bayesian analysis of a third, intermediate, case where the correlation matrix is of full rank for a finite T, but converges to a rank deficient matrix as T goes to infinity. So in the case of two regressors the correlation between them tends to ± 1 as $T \to \infty$. We call this the highly collinear case. Just as exact collinearity causes non-identification of the parameters, high collinearity can be viewed as weak identification of the parameters. This characterisation of the highly collinear case is in line with the notion of weak instruments and weak identification in the generalized method of moments, GMM, literature where the correlation of the instruments and the target variable is allowed to tend to zero with the sample size. See, for example, the survey by Stock, Wright, and Yogo (2002).

This representation allows us to examine the extent to which the Bayesian analysis is robust to the choice of prior. We analyse the asymptotic behaviour of the posterior mean and precision of the parameters of a linear regression model for exactly and highly collinear regressors, corresponding to the non-identified and weakly identified cases. Whereas in the identified case the posterior mean tends to its true value, in both the exactly collinear and highly collinear cases the posterior mean continues to depend on the priors even if $T \to \infty$, and the posterior precision increases at a rate slower than T. In the highly collinear case, the posterior means converge to normally distributed random variables whose mean and variance depend on the priors for coefficients and precision. The distribution degenerates to fixed points in the polar cases of either exact collinearity or strong identification. This analysis also suggests diagnostics for the highly collinear case.

The analysis is related to Poirier (1998), Koop et al. (2013), Baumeister and Hamilton (2015), and Basturk et al. (2017); all of which consider Bayesian analysis of unidentified or weakly identified models. The focus in Koop et al. (2013) was on the behaviour of the posterior precision of the coefficient when the parameter was not identified or only weakly identified, here the focus will also be on the behaviour of the posterior mean.

Phillips (2016) provides a frequentist analysis of a similar case of near singular regressions for both least squares and instrumental variable estimators, and shows that in the case of asymptotically collinear regressors the estimators will be inconsistent and converge to random variables. We obtain similar results, showing an equivalence of classical and Bayesian approaches in the weakly identified cases.[1]

Perhaps it is important to justify our use of asymptotics in Bayesian contexts, as many Bayesian are of the opinion that only finite T cases are relevant, and in such cases posterior means and precisions are well defined irrespective of whether the underlying parameters are identified, weakly identified or unidentified. We believe our analysis continues to be relevant even from such finite T perspectives, since it addresses how data updates (changes in T) affect the posterior means and precisions. In the unidentified and weakly identified cases our analysis suggests that posterior outcomes to be critically dependent on the choice of the priors; a dependence that does not diminish with successive Bayesian updates. It also follows that posterior mean of a weakly identified parameter (although well-defined for a finite T), will be much more sensitive to the choice of the priors as compared to the posterior mean of a strongly identified parameter.

The rest of the paper is organized as follows: Section 2 considers the exactly collinear case, where the parameters are not identified, to illustrate the role of the priors on the posterior means and precisions as $T \to \infty$. Section 3 considers the highly collinear case, where the parameters are weakly identified. The strength of identification can be measured by a signal to noise ratio and Section 4 discusses the use of this ratio as a diagnostic indicator for collinearity. Section 5 uses the empirical relationship between stock returns and dividend yields to illustrate the application

[1] Cheng et al. (2017) comment that there is little discussion on the large sample behaviour of the posterior mean and examine asymptotic properties of posterior means obtained from simulations.

of this diagnostic. Section 6 contains some concluding comments.

2 Exactly collinear regressors

We first consider the estimation of the posterior mean in the exactly collinear case as a benchmark for the highly collinear case. Consider the linear regression model

$$\mathbf{y} = \mathbf{X}\boldsymbol{\theta} + \mathbf{u}$$

where $\mathbf{y}$ is a $T \times 1$ vector of observations on the dependent variable, $\mathbf{X}$ is a $T \times k$ matrix of observations on the k regressors, $\boldsymbol{\theta}$ a $k \times 1$ vector of unknown parameters and $\mathbf{u}$ is a $T \times 1$ vector of errors distributed independently of $\mathbf{X}$ as $N(\mathbf{0}, \sigma^2 \mathbf{I}_T)$. An element of $\boldsymbol{\theta}$**,** say θ_i is the parameter of interest and to simplify the exposition below we often assume that σ^2 is known.[2]

The least squares estimator is given by

$$\widehat{\boldsymbol{\theta}} = \left(\mathbf{X}'\mathbf{X}\right)^{-1} \mathbf{X}'\mathbf{y}$$

when $(\mathbf{X}'\mathbf{X})$ is non-singular. When $(\mathbf{X}'\mathbf{X})$ is rank deficient it may still be possible to estimate functions of $\boldsymbol{\theta}$ say $\boldsymbol{\beta} = \boldsymbol{b}'\boldsymbol{\theta}$**.**

However, even with exact collinearity, the Bayesian posterior distribution of $\boldsymbol{\theta}$ is well defined. Suppose that the prior distribution of $\boldsymbol{\theta}$ is $N(\underline{\boldsymbol{\theta}}, \underline{\mathbf{H}}^{-1})$, where $\underline{\mathbf{H}}$, the prior precision matrix of $\boldsymbol{\theta}$, is a symmetric positive semi-definite matrix. Then based on a sample of T observations and known σ^2 the posterior mean of $\boldsymbol{\theta}$ is given by

$$\bar{\boldsymbol{\theta}}_T = \left(\sigma^{-2} T^{-1} \mathbf{X}'\mathbf{X} + T^{-1} \underline{\mathbf{H}}\right)^{-1} (\sigma^{-2} T^{-1} \mathbf{X}'\mathbf{y} + T^{-1} \underline{\mathbf{H}}\ \underline{\theta}), \tag{1}$$

and the covariance matrix of the posterior distribution of $\boldsymbol{\theta}$, denoted by $\bar{\mathbf{V}}$, is given by

$$\bar{\mathbf{V}} = \left(\sigma^{-2} \mathbf{X}'\mathbf{X} + \underline{\mathbf{H}}\right)^{-1}. \tag{2}$$

The posterior precision of θ_i, which we denote by $\bar{h}_{ii}$, is given by the inverse of the i^{th} diagonal element of $\bar{\mathbf{V}}$.

When $T^{-1}\mathbf{X}'\mathbf{X}$ is non-singular for all $T > k$, then $\bar{\boldsymbol{\theta}}_T$ converges in probability to $\boldsymbol{\theta}^0$, as $T \to \infty$, where $\boldsymbol{\theta}^0$ is the true value of $\boldsymbol{\theta}$. But when there are exact linear dependencies amongst the regressors and $\mathbf{X}$ is rank deficient, the posterior mean remains well defined for finite T since $\left(\sigma^{-2} T^{-1} \mathbf{X}'\mathbf{X} + T^{-1} \underline{\mathbf{H}}\right)^{-1}$ exists even if $(\mathbf{X}'\mathbf{X})^{-1}$ does not. We consider below what happens to the posterior means (and precisions) as $T \to \infty$.

To simplify the exposition we consider the relatively simple case where $k = 2$ and the regression model is given by

$$y_t = \theta_1 x_{1t} + \theta_2 x_{2t} + u_t,\ u_t \sim IIDN(0, \sigma^2), \tag{3}$$

where the y_t and the regressors are measured as deviations from their means, and where $\boldsymbol{\theta} = (\theta_1, \theta_2)'$ are the parameters of interest.

[2] Since σ^2 does not appear in the expressions for the main results, this is not a strong assumption.

Suppose that there is exact collinearity of the form $x_{2t} = \phi x_{1t}$ for all t, and ϕ is a known non-zero constant. In this case

$$T^{-1}\mathbf{X}'\mathbf{X} = s_T^2 \kappa_\phi \kappa_\phi', \;\; T^{-1}\mathbf{X}'\mathbf{y} = s_T^2 \hat{\beta}_T \kappa_\phi \tag{4}$$

where $\hat{\beta}_T = s_{yT}/s_T^2$, $s_{yT} = T^{-1}\sum_{t=1}^{T} y_t x_{1t}$, $s_T^2 = T^{-1}\sum_{t=1}^{T} x_{1t}^2 > 0$, for all T, and $\kappa_\phi = (1, \phi)'$. Also note that the estimable function is

$$\hat{\beta}_T \rightarrow_p \beta^0 = \theta_1^0 + \phi\, \theta_2^0. \tag{5}$$

In the case where x_{1t} and x_{2t} are perfectly correlated, θ_1^0 and θ_2^0 are not unique but defined by all values of θ_1 and θ_2 that lie on the line $\beta = \theta_1 + \phi\, \theta_2$, for all values $\beta \in \mathcal{R}$.

2.1 Posterior means in the exactly collinear case

We consider the limiting properties of the posterior means in the two regressor case, (3). Using (4) in (1) and after some algebra we have

$$\bar{\boldsymbol{\theta}}_T = \left(\kappa_\phi \kappa_\phi' + T^{-1}\mathbf{A}\right)^{-1} \left(\hat{\beta}_T \kappa_\phi + T^{-1}\mathbf{b}\right),$$

where

$$\mathbf{A} = (a_{ij}) = \left(\sigma^2/s_T^2\right) \begin{pmatrix} \underline{\mathrm{h}}_{11} & \underline{\mathrm{h}}_{12} \\ \underline{\mathrm{h}}_{12} & \underline{\mathrm{h}}_{22} \end{pmatrix},$$

$$\mathbf{b} = (b_i) = \frac{\sigma^2}{s_T^2}\underline{\mathbf{H}}\,\underline{\theta} = \frac{\sigma^2}{s_T^2} \begin{pmatrix} \underline{\mathrm{h}}_{11}\underline{\theta}_1 + \underline{\mathrm{h}}_{12}\underline{\theta}_2 \\ \underline{\mathrm{h}}_{12}\underline{\theta}_1 + \underline{\mathrm{h}}_{22}\underline{\theta}_2 \end{pmatrix}.$$

Therefore,

$$\bar{\theta}_{1,T} = \frac{\hat{\beta}_T\left(a_{22} - \phi a_{12}\right) + \phi\left(\phi b_1 - b_2\right) + T^{-1}\left(b_1 a_{22} - b_2 a_{12}\right)}{a_{11}\phi^2 - 2\phi a_{12} + a_{22} + T^{-1}(a_{11}a_{22} - a_{12}^2)}, \tag{6}$$

$$\bar{\theta}_{2,T} = \frac{b_2 - \phi b_1 - \hat{\beta}_T\left(a_{12} - \phi a_{11}\right) + T^{-1}\left(b_2 a_{11} - b_1 a_{12}\right)}{a_{11}\phi^2 - 2\phi a_{12} + a_{22} + T^{-1}(a_{11}a_{22} - a_{12}^2)}. \tag{7}$$

These are exact results, but to investigate the probability limits of the posterior means we only need to consider the first order terms.[3]

$$\bar{\theta}_{1,T} = \theta_1^0 + \frac{\left(\underline{\mathrm{h}}_{11}\phi^2 - \phi\underline{\mathrm{h}}_{12}\right)}{\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_1 - \theta_1^0\right) - \frac{\left(\phi\underline{\mathrm{h}}_{22} - \phi^2\underline{\mathrm{h}}_{12}\right)}{\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_2 - \theta_2^0\right) + O_p(T^{-1}), \tag{8}$$

and

$$\bar{\theta}_{2,T} = \theta_2^0 - \frac{\left(\phi\underline{\mathrm{h}}_{11} - \underline{\mathrm{h}}_{12}\right)}{\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_1 - \theta_1^0\right) + \frac{\left(\underline{\mathrm{h}}_{22} - \phi\underline{\mathrm{h}}_{12}\right)}{\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_2 - \theta_2^0\right) + O_p(T^{-1}), \tag{9}$$

In the case where $\underline{\mathrm{h}}_{12} = 0$, the results simplify to

$$p\lim_{T\to\infty}\left(\bar{\theta}_{1,T}\right) = \theta_1^0 + \frac{\phi^2\underline{\mathrm{h}}_{11}}{\underline{\mathrm{h}}_{11}\phi^2 + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_1 - \theta_1^0\right) - \frac{\phi\underline{\mathrm{h}}_{22}}{\underline{\mathrm{h}}_{11}\phi^2 + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_2 - \theta_2^0\right),$$

[3] The derivations are given in Appendix A1.

$$p\lim_{T\to\infty}(\bar{\theta}_{2,T}) = \theta_2^0 - \frac{\phi \underline{\mathrm{h}}_{11}}{\underline{\mathrm{h}}_{11}\phi^2 + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_1 - \theta_1^0\right) + \frac{\underline{\mathrm{h}}_{22}}{\underline{\mathrm{h}}_{11}\phi^2 + \underline{\mathrm{h}}_{22}}\left(\underline{\theta}_2 - \theta_2^0\right)$$

which are not equal to their true values and highlight the role of the prior means and precisions of both coefficients in the determination of the asymptotic posterior means. In the case where the prior precisions are set to be the same across the parameters and $\underline{\mathrm{h}}_{12} = 0$, (often done in practice) we have

$$p\lim_{T\to\infty}\left(\bar{\theta}_{1,T}\right) = \theta_1^0 + \frac{\phi^2}{1+\phi^2}\left(\underline{\theta}_1 - \theta_1^0\right) - \frac{\phi}{1+\phi^2}\left(\underline{\theta}_2 - \theta_2^0\right), \tag{10}$$

$$p\lim_{T\to\infty}(\bar{\theta}_{2,T}) = \theta_2^0 - \frac{\phi}{1+\phi^2}\left(\underline{\theta}_1 - \theta_1^0\right) + \frac{1}{1+\phi^2}\left(\underline{\theta}_2 - \theta_2^0\right), \tag{11}$$

and the limit of posterior means do not depend on the prior precisions, but do depend on both prior means, even asymptotically.

2.2 Posterior precisions in the exactly collinear case

Using (2) and noting that $x_{2t} = \phi x_{1t}$ we have

$$\begin{aligned}\bar{\mathbf{V}} &= \left(T\tilde{s}_T^2 \kappa_\phi \kappa_\phi' + \underline{\mathbf{H}}\right)^{-1} = \begin{pmatrix} T\tilde{s}_T^2 + \underline{\mathrm{h}}_{11} & T\tilde{s}_T^2\phi + \underline{\mathrm{h}}_{12} \\ T\tilde{s}_T^2\phi + \underline{\mathrm{h}}_{12} & T\tilde{s}_T^2 + \phi^2\underline{\mathrm{h}}_{22}\end{pmatrix}^{-1} \\ &= \frac{1}{\left(T\tilde{s}_T^2 + \underline{\mathrm{h}}_{11}\right)\left(T\tilde{s}_T^2 + \phi^2\underline{\mathrm{h}}_{22}\right) - \left(T\tilde{s}_T^2\phi + \underline{\mathrm{h}}_{12}\right)^2}\begin{pmatrix} T\tilde{s}_T^2 + \phi^2\underline{\mathrm{h}}_{22} & -T\tilde{s}_T^2\phi - \underline{\mathrm{h}}_{12} \\ -T\tilde{s}_T^2\phi - \underline{\mathrm{h}}_{12} & T\tilde{s}_T^2 + \underline{\mathrm{h}}_{11}\end{pmatrix},\end{aligned}$$

where $\tilde{s}_T^2 = s_T^2/\sigma^2$. The posterior precison of θ_1 is given by the inverse of the first element of $\bar{\mathbf{V}}$, namely

$$\bar{h}_{11} = \frac{\left(T\tilde{s}_T^2 + \underline{\mathrm{h}}_{11}\right)\left(T\tilde{s}_T^2 + \phi^2\underline{\mathrm{h}}_{22}\right) - \left(T\tilde{s}_T^2\phi + \underline{\mathrm{h}}_{12}\right)^2}{T\tilde{s}_T^2 + \phi^2\underline{\mathrm{h}}_{22}},$$

which gives the following result for the average precision of θ_1

$$T^{-1}\bar{h}_{11} = (\tilde{s}_T^2 + T^{-1}\underline{\mathrm{h}}_{11}) - \left(\phi\tilde{s}_T^2 + T^{-1}\underline{\mathrm{h}}_{12}\right)\left(\phi^2\tilde{s}_T^2 + T^{-1}\underline{\mathrm{h}}_{22}\right)^{-1}\left(\phi\tilde{s}_T^2 + T^{-1}\underline{\mathrm{h}}_{21}\right),$$

and after some algebra yields

$$T^{-1}\bar{h}_{11} = T^{-1}\tilde{s}_T^2\left\{\frac{(\underline{\mathrm{h}}_{22}/\tilde{s}_T^2) + (\underline{\mathrm{h}}_{11}/\tilde{s}_T^2)\phi^2 + (\underline{\mathrm{h}}_{11}/\tilde{s}_T^2)T^{-1}(\underline{\mathrm{h}}_{22}/\tilde{s}_T^2) - 2\phi\underline{\mathrm{h}}_{21}/\tilde{s}_T^2 - T^{-1}\left(\underline{\mathrm{h}}_{21}/\tilde{s}_T^2\right)^2}{\phi^2 + T^{-1}(\underline{\mathrm{h}}_{22}/\tilde{s}_T^2)}\right\}.$$

It now readily follows that $\lim_{T\to\infty} T^{-1}\bar{h}_{11} = 0$, namely for any choice of priors and finite values of $\tilde{s}_T^2$, the average precision of θ_1 will tend to zero when the regressors are exactly collinear. This result contrasts to the identified case where the average precision tends to a non-zero constant. It is also instructive to consider the special case when the priors of θ_1 and θ_2 are independent, namely $\underline{\mathrm{h}}_{12} = \underline{\mathrm{h}}_{21} = 0$. In this case the above expression simplifies to

$$\bar{h}_{11} = \frac{\underline{\mathrm{h}}_{22} + \phi^2\underline{\mathrm{h}}_{11} + T^{-1}\underline{\mathrm{h}}_{11}\underline{\mathrm{h}}_{22}/\tilde{s}_T^2}{\phi^2 + T^{-1}(\underline{\mathrm{h}}_{22}/\tilde{s}_T^2)}.$$

Hence, the posterior precision ($\bar{h}_{11}$) of the unidentified parameter, θ_1, differs from its prior precision ($\underline{h}_{11}$) for all T, and as $T \to \infty$, even though θ_1 and θ_2 are assumed to be a priori independent. Also, for T sufficiently large we have

$$\lim_{T\to\infty} \bar{h}_{11} = \underline{h}_{11} + \phi^{-2}\underline{h}_{22},$$

which shows that the posterior precision is bounded in T, in contrast to the posterior precision of an identified parameter that rises linearly with T.

The extent to which the posterior precision deviates from the prior precision is determined by $\underline{h}_{22}/\phi^2$. It is also worth noting, however, that as T increases the posterior precision declines. This could be viewed as an indication that θ_1 is not identified. In the case where a parameter is identified we would expect the posterior precision to rise with T and eventually dominate the prior precision.

3 Highly collinear regressors

In practice, the case of exactly collinear regressors is only of pedagogical interest. A more relevant case arises when the regressors are highly collinear. The issue is how to define highly collinear. Here, following the literature on weak identification, we consider a case where the correlation matrix is full rank for a finite T, but tends to a rank deficient matrix as $T \to \infty$. In this way we are able to investigate the role of the priors in regression analysis when the regressors are highly collinear and are expected to remain so even if we consider larger data sets. With this in mind we model the collinearity of the regressors in (3) by

$$x_{2t} = \phi x_{1t} + \frac{\delta_T}{\sqrt{T}} v_t, \tag{12}$$

where v_t is a stationary process with zero means, distributed independently of x_{1t} and u_t such that

$$s_{vv,T} = T^{-1}\sum_{t=1}^{T} v_t^2 \to_p \sigma_v^2, \quad s_T^2 = T^{-1}\sum_{t=1}^{T} x_{1t}^2 \to_p \sigma_1^2, \tag{13}$$

$$T^{-1/2} s_T^{-2}\sum_{t=1}^{T} x_{1t}v_t \to_d N(0,\sigma_v^2), \quad T^{-1/2}\sum_{t=1}^{T} u_t v_t \to_d N(0,\sigma^2\sigma_v^2). \tag{14}$$

The coefficient δ_T in (12) controls the degree of collinearity between the two regressors. It is clear that the correlation between x_{1t} and x_{2t} is not perfect when T is finite, but when δ_T is constant, it tends to unity as $T \to \infty$. More specifically, denoting the correlation coefficient of x_{1t} and x_{2t} by ρ_T, we have

$$\rho_T = \frac{\phi + \frac{\delta_T}{\sqrt{T}}\left(\frac{T^{-1/2}\sum_{t=1}^{T} x_{1t}v_t}{s_T^2}\right)}{\sqrt{\phi^2 + 2\phi\frac{\delta_T}{\sqrt{T}}\left(\frac{T^{-1/2}\sum_{t=1}^{T} x_{1t}v_t}{s_T^2}\right) + \frac{\delta_T^2}{T}\left(\frac{s_{vv,T}}{s_T^2}\right)}},$$

which in view of (13) and (14) yields

$$\rho_T = \left(\frac{\phi}{|\phi|}\right)\left[1 + O_p\left(\frac{\delta_T}{\sqrt{T}}\right)\right]. \tag{15}$$

In finite samples ρ_T could take any value over the range $(-1, 1)$, but tends to ± 1, as $T \to \infty$. It tends to 1 if $\phi > 0$, and to -1 if $\phi < 0$. The above result can also be written equivalently as

$$\rho_T^2 = 1 + O_p\left(\frac{\delta_T}{\sqrt{T}}\right).$$

There is a one-to-one relationship between the degree of correlation of x_{1t} and x_{2t} and the degree of identifiability of θ_1 and θ_2. The different cases can be characterized in terms of δ_T. In the perfectly collinear case $\delta_T = 0$, for all T, and in the highly collinear case of weak identification δ_T is bounded in T. Strong identification requires $\delta_T^2 = \ominus(T)$ where $\ominus(T)$ denotes that δ_T^2 rises at the *same* rate as T, such that $\rho_T^2 < 1$, for all values of T, including as $T \to \infty$.[4]

As noted above, this formulation is akin to the treatment of weak identification employed in the GMM literature. Where we have $\rho_T^2 \to 1$, as $T \to \infty$, in that literature a reduced form coefficient goes to zero as $T \to \infty$. For instance, Staiger and Stock (1997) consider the case of a single right hand side endogenous variable with reduced form coefficient π and introduce weak instrument asymptotics as a local to zero alternative of the form $\pi = \delta/\sqrt{T}$, where δ is a constant and T is the sample size. In a specification that is even more similar to ours, Sanderson and Windmeijer (2016) examine the case where there are two right hand side endogenous variables and consider weak instrument asymptotics local to a rank reduction of one of the form

$$\boldsymbol{\pi}_1 = \alpha\boldsymbol{\pi}_2 + \frac{\boldsymbol{\delta}}{\sqrt{T}}, \tag{16}$$

where $\boldsymbol{\pi}_1$ and $\boldsymbol{\pi}_2$ are vectors of parameters in the two reduced form equations, δ is a vector of constants and T is the sample size. Where (16) has the relation between the reduced form parameters a deterministic functions of the sample size, (12) postulates a stochastic relation between the regressors such that their correlation coefficient, ρ_T, tends to unity at the rate of $\delta_T/\sqrt{T}$, which corresponds to the local parameterization used in the weak instrument literature.

3.1 Posterior mean in the highly collinear case

The posterior mean of θ_1, namely $\bar{\theta}_{1,T}$, is derived in Appendix A2 and is given by (27)

$$\bar{\theta}_{1,T} = \theta_1^0 + \frac{\phi\left(\underline{\mathrm{h}}_{11}\phi - \underline{\mathrm{h}}_{12}\right)}{\lambda_T^2 + \boldsymbol{\psi}'\underline{\mathbf{H}}\boldsymbol{\psi}}\left(\underline{\theta}_1 - \theta_1^0\right) - \frac{\phi\left(\underline{\mathrm{h}}_{22} - \phi\underline{\mathrm{h}}_{12}\right)}{\lambda_T^2 + \boldsymbol{\psi}'\underline{\mathbf{H}}\boldsymbol{\psi}}\left(\underline{\theta}_2 - \theta_2^0\right)$$
$$- \left(\frac{\beta^0\phi\lambda_T}{\lambda_T^2 + \boldsymbol{\psi}'\underline{\mathbf{H}}\boldsymbol{\psi}}\right)\left(T^{-1/2}\sum_{t=1}^{T}\frac{v_t u_t}{\sigma_v\sigma}\right) + O_p\left(T^{-1/2}\right).$$

[4] The notation $f = \ominus(T)$ differs from the standard big O notation, $f = O(T)$. The latter provides an upper bound on the expansion rate of the function in terms of T, whilst the former refers to the exact rate at which the function rises with T.

where $\boldsymbol{\psi} = (\phi, -1)'$, $\underline{\mathbf{H}} = \left(\underline{\mathrm{h}}_{ij}\right)$, and $\lambda_T^2 = \delta_T^2 \sigma_v^2 / \sigma^2$ is a signal-noise ratio that provides a summary measure of the relative importance of the collinearity for the analysis of the posterior mean. The above result generalizes equation (8), derived for the exactly collinear case, and reduces to it when $\delta_T = 0$.

Denoting the limit of δ_T as $T \to \infty$, by δ, (which could be 0 or ∞), then the posterior mean tends to a normal distribution that depends on prior means and precisions. More specifically we have

$$\bar{\theta}_{1,T} \to_d N\left(\mu, \omega^2\right), \text{ as } T \to \infty,$$

where

$$\mu = \theta_1^0 + \frac{\phi\left(\underline{\mathrm{h}}_{11}\phi - \underline{\mathrm{h}}_{12}\right)}{\lambda^2 + \psi' \underline{\mathbf{H}} \psi}\left(\underline{\theta}_1 - \theta_1^0\right) - \frac{\phi\left(\underline{\mathrm{h}}_{22} - \phi \underline{\mathrm{h}}_{12}\right)}{\lambda^2 + \psi' \underline{\mathbf{H}} \psi}\left(\underline{\theta}_2 - \theta_2^0\right),$$

and

$$\omega^2 = \frac{\left(\beta^0 \phi\right)^2 \lambda^2}{\left(\lambda^2 + \psi' \underline{\mathbf{H}} \psi\right)^2}.$$

The frequentist results in Phillips (2016, Theorem 1) match the above findings that the posterior means do not converge to their true values and are normally distributed random variables, and show the general equivalence of classical and Bayesian approaches even for weakly identified cases.

The nature of the limiting property of the posterior mean, $\bar{\theta}_{1,T}$, critically depends on the (population) signal-to-noise ratio $\lambda^2 = \delta^2 \sigma_v^2 / \sigma^2$. The signal, $\delta^2 \sigma_v^2$, measures the extent to which x_{1t} and x_{2t} have "independent" variation in the regression of x_{2t} on x_{1t}, (12), while σ^2 is the measure of the noise in the regression. As will be discussed below this provides a measure of the strength of identification. The distribution of $\bar{\theta}_{1,T}$ degenerates to a fixed value only under the two polar cases of exact collinearity and strong identification. In the case of exact collinearity $\delta = \lambda = 0$, and we have $\omega^2 = 0$, and μ is the limit (as $T \to \infty$) of the posterior mean of θ_1 in the exactly collinear case discussed in Section 2.1. In the case where the parameters are strongly identified, $\delta_T^2 = \ominus(T)$, such that $\delta_T^2 / T \to c > 0$, then $\omega^2 \to 0$, and $\mu \to \theta_1^0$.

3.2 Posterior precision in the highly collinear case

Turning to posterior precisions, using (2) we have

$$\bar{\mathbf{V}}^{-1} = T\tilde{s}_T^2 \begin{pmatrix} 1 & \phi \\ \phi & \phi^2 \end{pmatrix} + \begin{pmatrix} \underline{\mathrm{h}}_{11} & \underline{\mathrm{h}}_{12} + \delta_T \left(T^{1/2} s_{1v,T}/\sigma^2\right) \\ \underline{\mathrm{h}}_{12} + \delta_T \left(T^{1/2} s_{1v,T}/\sigma^2\right) & \underline{\mathrm{h}}_{22} + \lambda_{21,T}^2 + 2\phi\delta_T \left(T^{1/2} s_{1v,T}/\sigma^2\right) \end{pmatrix}, \tag{17}$$

where as before $\tilde{s}_T^2 = s_T^2 / \sigma^2$, and

$$s_{1v,T} = T^{-1} \sum_{t=1}^{T} x_{1t} v_t,\ s_{vv,T} = T^{-1} \sum_{t=1}^{T} v_t^2,\ \lambda_{21,T}^2 = \delta_T^2 \left(s_{vv,T}/\sigma^2\right)$$

The posterior precision of θ_1 is given by the inverse of the first element of $\bar{\mathbf{V}}$. The derivations are given in Appendix A3, where it is shown that,

$$\bar{h}_{11,T} = \frac{\tilde{s}_T^2 \left(\underline{\mathrm{h}}_{11}\phi^2 + \lambda_T^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22}\right)}{\phi^2\tilde{s}_T^2 + 2\chi_T\phi T^{-1}z_T + T^{-1}\underline{\mathrm{h}}_{22} + T^{-1}\lambda_T^2} + \frac{-T^{-1}\chi_T^2 z_T^2 + 2\chi_T\left(\underline{\mathrm{h}}_{11}\phi - \underline{\mathrm{h}}_{12}\right)T^{-1}z_T}{\phi^2\tilde{s}_T^2 + 2\chi_T\phi T^{-1}z_T + T^{-1}\underline{\mathrm{h}}_{22} + T^{-1}\lambda_T^2}$$
$$\frac{+\underline{\mathrm{h}}_{11}T^{-1}\lambda_T^2 + T^{-1}\underline{\mathrm{h}}_{11}\underline{\mathrm{h}}_{22} - T^{-1}\underline{\mathrm{h}}_{12}^2}{\phi^2\tilde{s}_T^2 + 2\chi_T\phi T^{-1}z_T + T^{-1}\underline{\mathrm{h}}_{22} + T^{-1}\lambda_T^2}, \tag{18}$$

where $\chi_T = \delta_T\sigma_v\sigma_{x_1}/\sigma^2$,

$$z_T = \frac{T^{1/2}s_{1v,T}}{\sigma_{x_1}\sigma_v} = T^{-1/2}\sum_{t=1}^{T}\frac{x_{1t}v_t}{\sigma_{x_1}\sigma_v} \to_d N(0,1).$$

Hence, for a finite T the posterior precision of θ_1 is a nonlinear function of the random variable z_T, and itself is also a random variable. The limiting properties of $\bar{h}_{11,T}$, crucially depends on the limiting properties of δ_T (see (12)) as $T \to \infty$. In the highly collinear case, δ_T is bounded in T and we have

$$p\lim_{T\to\infty}\bar{h}_{11,T} = \frac{\left(\lambda^2 + \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22}\right)}{\phi^2} = \frac{\lambda^2 + \psi'\underline{\mathbf{H}}\psi}{\phi^2}.$$

where as before $\lambda^2 = \delta^2\sigma_v^2/\sigma^2 = p\lim_{T\to\infty}\delta_T^2\left(s_{vv,T}/\sigma^2\right)$. Similarly,

$$p\lim_{T\to\infty}\bar{h}_{22,T} = \lambda^2 + \phi^2\underline{\mathrm{h}}_{11} - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} = \lambda^2 + \psi'\underline{\mathbf{H}}\psi.$$

Hence, in the highly collinear case (where θ_1 and θ_2 are weakly identified), the posterior precision tends to a finite limit, which is qualitatively the same conclusion obtained for the exactly collinear case. Finally, in the strongly identified case, where $\delta_T^2/T \to c^2 > 0$, then $\lim_{T\to\infty}\left(T^{-1}\lambda_T^2\right) = c^2\sigma_v^2/\sigma^2$, and using this results in (18) we have

$$p\lim_{T\to\infty}T^{-1}\bar{h}_{11,T} = \frac{\lim_{T\to\infty}\left(T^{-1}\lambda_T^2\right)}{\phi^2\sigma_{x_1}^2/\sigma^2 + \lim_{T\to\infty}\left(T^{-1}\lambda_T^2\right)}$$
$$= \frac{c^2\sigma_v^2/\sigma^2}{\phi^2\sigma_{x_1}^2/\sigma^2 + c^2\sigma_v^2/\sigma^2} = \frac{c^2\sigma_v^2}{\phi^2\sigma_{x_1}^2 + c^2\sigma_v^2} > 0.$$

Also using (12) it follows that $\phi^2\sigma_{x_1}^2 + c^2\sigma_v^2 = \sigma_{x_2}^2$, and hence in the strongly identified case

$$p\lim_{T\to\infty}T^{-1}\bar{h}_{11,T} = 1 - \rho_{12}^2,$$

where ρ_{12} is the population correlation coefficient of x_{1t} and x_{2t}. Therefore, as to be expected, in contrast to the highly collinear case, the posterior precision of strongly identified coefficients rise with T such that the average precision, $T^{-1}\bar{h}_{11,T}$, tends to a strictly positive constant. Also, as to be expected, the posterior precision does not depend on the priors when T is sufficiently large and the regression coefficients are strongly identified.

Finally, it is worth noting that the limiting property of the average precision is qualitatively the same irrespective of whether the parameters are not identified, the exactly collinear case, or weakly identified, the highly collinear case. In both cases the average precision tends to zero with T, although the rates at which this occurs does depend on whether the underlying parameter is weakly identified or not identified. This common feature does not extend to the posterior mean, whose limiting properties differ between the weakly identified and not identified cases.

4 Diagnostics for collinearity

As noted above, for large T the strength of identification is measured by the signal-to-noise ratio $\lambda^2 = \delta^2\sigma_v^2/\sigma^2$. The numerator, $\delta^2\sigma_v^2$, can be estimated from the OLS residuals of the regression of x_{2t} on x_{1t}, corresponding to (12), namely

$$\widehat{\delta^2\sigma_v^2} = \sum_{t=1}^{T}\left(x_{2t} - \hat{\phi}x_{1t}\right)^2.$$

The denominator, σ^2, can be estimated consistently from the regression of y_t on x_{1t} and x_{2t}, even if x_{1t} and x_{2t} are perfectly correlated.[5] A consistent estimator of λ_T^2 is now given by:

$$\hat{\lambda}_T^2 = \frac{\widehat{\delta^2\sigma_v^2}}{\sigma^2} = \frac{\sum_{t=1}^{T}\left(x_{2t} - \hat{\phi}x_{1t}\right)^2}{T^{-1}\sum_{t=1}^{T}\left(y_t - \hat{\theta}_1 x_{1t} - \hat{\theta}_2 x_{2t}\right)^2}. \tag{19}$$

This collinearity diagnostic can also be written equivalently as

$$\hat{\lambda}_T^2 = \frac{T\hat{\sigma}_{2:1}^2}{\hat{\sigma}^2}, \tag{20}$$

where $\hat{\sigma}_{2:1}^2$ is the estimator of the error variance of the regression of x_{2t} on x_{1t}, and $\hat{\sigma}^2$ is the estimator of the error variance of the regression model.

The null hypothesis of interest is weak identification of θ_1 or θ_2, and can be written as

$$H_0: \ \delta_T^2 = c^2,$$

where c is a positive constant. The alternative hypothesis of strong identification is defined by

$$H_1: \ \delta_T^2 = \ominus(T).$$

Using (12), under the null hypothesis (and noting that all variables are measured as deviations from their means) we have

$$T\hat{\sigma}_{2:1}^2 = \mathbf{x}_2'\mathbf{M}_1\mathbf{x}_2 = c^2\left(\frac{\mathbf{v}'\mathbf{M}_1\mathbf{v}}{T}\right),$$

and hence

$$\hat{\lambda}_T^2 = \frac{\left(\frac{c^2\sigma_v^2}{\sigma^2}\right)\left(\frac{\mathbf{v}'\mathbf{M}_1\mathbf{v}}{T\sigma_v^2}\right)}{\frac{\mathbf{u}'\mathbf{M}\mathbf{u}}{T\sigma^2}},$$

where $\mathbf{v} = (v_1, v_2, ..., v_T)'$, $\mathbf{u} = (u_1, u_2, ..., u_T)'$, $\mathbf{M}_1 = \mathbf{I}_T - \mathbf{X}_1(\mathbf{X}_1'\mathbf{X}_1)^{-1}\mathbf{X}_1$, $\mathbf{M} = \mathbf{I}_T - \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}$, $\mathbf{X}_1 = (\tau_T, \mathbf{x}_1)$, $\mathbf{X} = (\tau_T, \mathbf{x}_1, \mathbf{x}_2)$, and τ_T is a $T \times 1$ vector of ones. For T large and by the Slutsky Theorem

$$\hat{\lambda}_T^2 \overset{a}{\sim} \lambda^2\left(\frac{\mathbf{v}'\mathbf{M}_1\mathbf{v}}{T\sigma_v^2}\right),$$

where $\lambda^2 = \left(\frac{c^2\sigma_v^2}{\sigma^2}\right)$, and $\hat{\lambda}_T^2 \rightarrow_p \lambda^2$. Consider now the standardized test statistic

$$\Delta_T' = \sqrt{\frac{T-2}{2}}\left[\left(\frac{T}{T-2}\frac{\hat{\lambda}_T^2}{\lambda^2} - 1\right)\right], \tag{21}$$

[5] See Section 3.12 of Pesaran (2015).

and suppose that v_t is $IIDN(0, \sigma_v^2)$. Then, since $\mathbf{M}_1$ is an idempotent matrix of rank $T-2$, we have

$$\Delta_T' = \frac{\sigma_v^{-2}\mathbf{v}'\mathbf{M}_1\mathbf{v} - (T-2)}{\sqrt{2\,(T-2)}} = \frac{\sum_{i=1}^{T-2}(\xi_i^2 - 1)/\sqrt{2}}{\sqrt{(T-2)}},$$

where ξ_i^2 are $IID(1,2)$. Hence, under H_0, $\Delta_T' \rightarrow_d N(0,1)$. In practice, one could use the asymptotically equivalent simpler version of Δ_T', given by

$$\Delta_T = \sqrt{\frac{T}{2}}\left(\frac{\hat{\lambda}_T^2}{\lambda^2} - 1\right) \rightarrow_d N(0,1), \text{ under } H_0 \text{ and as } T \rightarrow \infty. \tag{22}$$

The implementation of the test is complicated by the fact that Δ_T depends on the nuisance constant λ^2, though a convenient choice would be to set $\lambda^2 = 1$.

Due to the dependence of Δ_T on λ^2, an alternative strategy would be to use $\hat{\lambda}_T^2$ purely as an indicator of high collinearity, with low values interpreted as evidence of weak identification of θ_1 (or θ_2). Recall that under exact collinearity, $\hat{\lambda}_T^2 = 0$, and it might be expected to be close to zero in the highly collinear case. If identification is strong we would expect $\hat{\lambda}_T^2$ to rise with T. But if identification is weak, in the sense defined above, we would not expect $\hat{\lambda}_T^2$ to rise with T. Accordingly, collinearity is likely to be a problem if $\hat{\lambda}_T^2$ is small and does not increase much as T increases. This suggests estimating $\hat{\lambda}_T^2$ using expanding observation windows starting with the first T_0 observations and then plotting $\hat{\lambda}_\tau^2$, for $\tau = T_0, T_0+1, ..., T$ and check the rate at which $\hat{\lambda}_\tau^2$ rises with τ. Equivalently one could consider whether $\tau^{-1}\hat{\lambda}_{i\tau}^2$ was constant as τ increased.

A scaled version of the high collinearity diagnostic statistic, $\hat{\lambda}_T^2$, is also related to the R^2 rule of thumb due to Klein (1962, p101) that considers multicollinearity is likely to be a problem if $R_{12}^2 > R_y^2$, where R_{12}^2 $(= R_{21}^2)$ is the squared correlation coefficient of x_{1t} and x_{2t}, and R_y^2 is the multiple correlation coefficient of the regression model, since.

$$\left(\frac{Var(y)}{Var(x_1)}\right)\hat{\lambda}_T^2 = T\left(\frac{1 - R_{12}^2}{1 - R_y^2}\right).$$

The above results and the diagnostic given by (20) generalize to regression models with more than two regressors. In the case of a linear regression model with k regressors (not counting the intercept) the high collinearity diagnostic statistic for the i^{th} regressors is given by

$$\hat{\lambda}_{iT}^2 = \frac{T\hat{\sigma}_i^2}{\hat{\sigma}^2}, \text{ for } i = 1, 2, ..., k, \tag{23}$$

where $\hat{\sigma}_i^2$ is the estimator of the error variance of the regression of the i^{th} regressor on the remaining regressors, and $\hat{\sigma}^2$ is the estimator of the underlying regression model. Once again expanding window estimates of $T^{-1}\hat{\lambda}_{iT}^2$ can provide useful indication of the weak identification of the i^{th} coefficient in the regression model. There would be a collinearity problem if $\hat{\lambda}_{i\tau}^2$ for $\tau = T_0, T_0+1, ..., T$ do not exhibit an upward trend as the window size is increased. The relative size of this measure for different regressors also indicates their relative sensitivity to collinearity.

In cases where T is short one could follow Koop et al. (2013) consider estimates of $T^{-1}\hat{\lambda}_{i,T}^2$ using bootstrapped samples generated using the regression model and the marginal regressions of x_{it} on the remaining regressors.

5 An empirical illustration

We use a familiar example of predicting excess stock returns by the dividend yield. We use Robert Shiller's online monthly data over the period 1871m1 2017m8.[6] Monthly real excess returns on Standard & Poor 500 (SP500), denoted by y_t, are computed as

$$y_t = \left(\frac{s_t - s_{t-1}}{s_{t-1}}\right) + \frac{d_t}{s_{t-1}} - r_{t-1},$$

where $s_t = SP500_t/CPI_t$, $d_t = DIV_t/(12 * CPI_t)$, $SP500_t$ is the SP500 price index, CPI_t is the consumer price index, DIV_t is the annual rate of dividends paid on SP500, and r_t is the real return on ten year US government bond computed as

$$r_t = \left[(1 + GS10_t/100)^{1/12} - 1\right] - \pi_t,$$

where $GS10_t$ is the 10-Year Treasury Constant Maturity Rate per annum, and π_t is the rate of inflation computed as $\pi_t = (CPI_t - CPI_{t-1})/CPI_{t-1}$. The dividend yield variable is defined by $x_t = \ln(d_t/s_t)$. We consider the predictive regressions

$$y_t = \alpha_y + \lambda_y y_{t-1} + \theta_1 x_{1t} + \theta_2 x_{2t} + u_t, \tag{24}$$

where $x_{it} = x_{t-i}$, for $i = 1, 2$, and compute recursive estimates of $\sigma^2 = Var(u_t)$ using expanding windows starting with $1872m1$ and ending at $2017m8$. We denote these recursive estimates by $\hat{\sigma}^2_\tau$. We also consider the recursive estimates of the following auxiliary regression

$$x_{1t} = \alpha_x + \phi x_{2t} + \lambda_x y_{t-1} + v_t, \tag{25}$$

and compute the recursive estimates of $\sigma_1^2 = Var(v_t)$, which we denote by $\hat{\sigma}^2_{1,\tau}$. The recursive estimates of the collinearity indicator of θ_1 is now given by

$$\tau^{-1}\hat{\lambda}^2_{1,\tau} = \frac{\hat{\sigma}^2_{1,\tau}}{\hat{\sigma}^2_\tau}.$$

In the case where θ_1 is strongly identified we would expect $\hat{\lambda}^2_{1,\tau}$ to rise *linearly* with τ, or equivalently that $\tau^{-1}\hat{\lambda}^2_{1,\tau}$ to remain reasonably constant over the period $1872m1 - 2017m8$. To avoid the large sample variations when τ is small we drop the first 100 observations and show the values of $\tau^{-1}\hat{\lambda}^2_{1,\tau}$ over the period $\tau = 1880m1 - 2017m8$ in Figure 1 below.

[6] See http://www.econ.yale.edu/~shiller/data.htm.

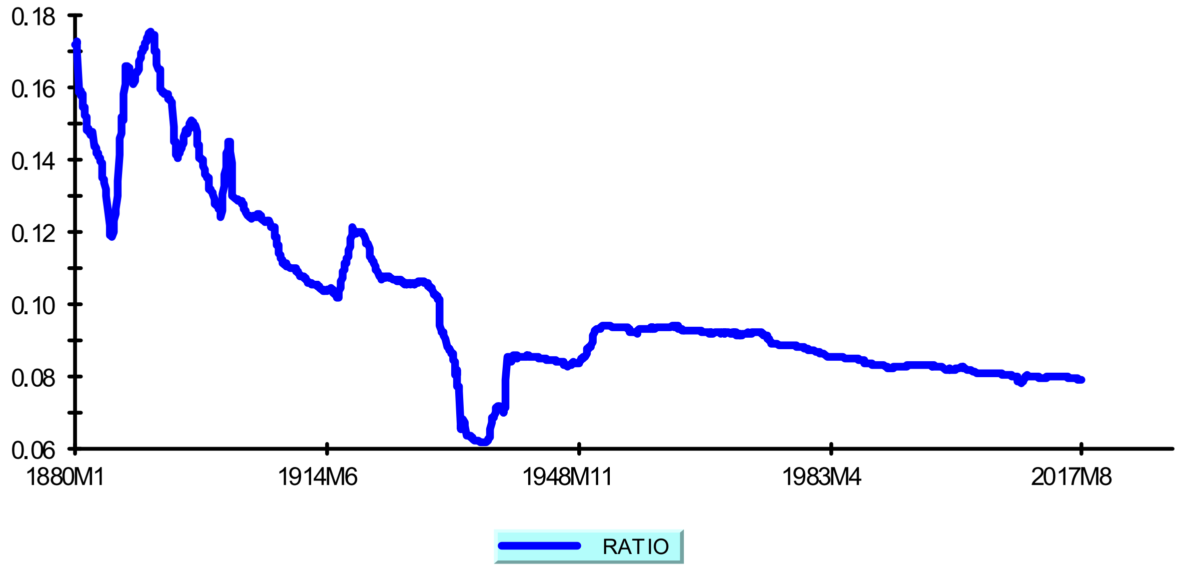

Figure 1: The Recursive Estimates of $\tau^{-1}\hat{\lambda}^2_{1\tau}$ for the Dividend Yield Variable, x_{1t} in the Excess Return Regression (24)

As can be seen, the high collinearity indicator has been falling over the sample with the exception of a brief period after the stock market crash of 1929. This suggests that the coefficients of the dividend yield variables are likely to be weakly identified.

6 Conclusion

We have considered a Bayesian approach to collinearity among regressors. In the multicollinear case, where there are high but not perfect correlations, the coefficients are strongly identified and as the sample size gets large the Bayesian posterior mean converges to the true value of the parameter. In the exactly collinear case the posterior means converge to constants which depend on the priors and the posterior precision is bounded in T. In the highly collinear case where there are high correlations in finite samples and the data matrix becomes singular in the limit as $T \to \infty$, the posterior means converge to normally distributed random variables whose mean and variance depend on the priors for coefficients and precision. The distribution of this random variable degenerates to fixed points in the polar cases of either where the parameters are not identified, exact collinearity, or where the parameters are strongly identified. The analysis suggests an indicator of collinearity, $\hat{\lambda}^2_{i,T}$, a measure of the signal to noise ratio, for the *ith* regressor, which is zero in the exactly collinear case and rises with T in the strongly identified case. It is related to the R^2 rule of thumb due to Klein. We derive the distribution of this measure, which would allow it to be used as the basis for a test, except that it depends on a nuisance statistic. Thus it seems more useful as an estimated diagnostic for colinearity, since the size of $\hat{\lambda}^2_{i,T}$ and how it changes with T can be indicative of highly collinear relations.

Because the posterior mean can go to a random variable as the sample size increases in the highly collinear case of weak identification, it is not a reliable indicator. The posterior precision, which increases with T in the strongly identified case, provides a better indicator and our suggested diagnostic can be seen as a frequentist counterpart to the posterior precision.

Appendices

A1. Derivation of the probability limit for the posterior mean, $\bar{\boldsymbol{\theta}}_T$, in the exactly colinear case

First consider $\bar{\theta}_{1,T}$ given by (6):

$$\begin{aligned}\bar{\theta}_{1,T} &= \frac{\hat{\beta}_T\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)+\phi\left[\phi\underline{h}_{11}\underline{\theta}_1-\underline{h}_{12}\underline{\theta}_1+\phi\underline{h}_{12}\underline{\theta}_2-\underline{h}_{22}\underline{\theta}_2\right]}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}}+O_p(T^{-1}),\\ &= \frac{\hat{\beta}_T\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)+\phi\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)\underline{\theta}_1+\phi\left(\phi\underline{h}_{12}-\underline{h}_{22}\right)\underline{\theta}_2}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}}+O_p(T^{-1}).\end{aligned}$$

Then taking probability limits (noting that $\hat{\beta}_T\to_p \theta_1^0+\phi\ \theta_2^0$), we have

$$\begin{aligned}p\lim_{T\to\infty}\left(\bar{\theta}_{1,T}\right) &= \frac{\theta_1^0\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)+\phi\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)\underline{\theta}_1+\theta_2^0\left(\phi\underline{h}_{22}-\phi^2\underline{h}_{12}\right)-\phi\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\underline{\theta}_2}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}},\\ &= \frac{\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\theta_1^0+\phi\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)\underline{\theta}_1+\phi\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\left(\theta_2^0-\underline{\theta}_2\right)}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}},\\ &= \theta_1^0+\frac{\phi\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)\left(\underline{\theta}_1-\theta_1^0\right)-\phi\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\left(\underline{\theta}_2-\theta_2^0\right)}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}}.\end{aligned}$$

Similarly,

$$\bar{\theta}_{2,T}=\frac{\hat{\beta}_T\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)+\left(\underline{h}_{12}-\phi\underline{h}_{11}\right)\underline{\theta}_1+\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\underline{\theta}_2}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}}+O_p(T^{-1}),$$

and

$$\begin{aligned}p\lim_{T\to\infty}(\bar{\theta}_{2,T}) &= \frac{\left(\theta_1^0+\phi\theta_2^0\right)\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)+\left(\underline{h}_{12}-\phi\underline{h}_{11}\right)\underline{\theta}_1+\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\underline{\theta}_2}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}},\\ &= \frac{\phi\theta_2^0\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)+\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\underline{\theta}_2+\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)\left(\theta_1^0-\underline{\theta}_1\right)}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}},\\ &= \theta_2^0+\frac{-\left(\phi\underline{h}_{11}-\underline{h}_{12}\right)\left(\underline{\theta}_1-\theta_1^0\right)+\left(\underline{h}_{22}-\phi\underline{h}_{12}\right)\left(\underline{\theta}_2-\theta_2^0\right)}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}}.\end{aligned}$$

Let $\xi'=(-\phi,1)$, so $X\xi=\mathbf{0}$ then $\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}=\xi'\underline{\mathbf{H}}\xi$, and

$$\begin{aligned}p\lim_{T\to\infty}\left(\bar{\boldsymbol{\theta}}_T\right) &= \boldsymbol{\theta}^0+\frac{1}{\underline{h}_{11}\phi^2-2\phi\underline{h}_{12}+\underline{h}_{22}}\begin{pmatrix}\phi^2 & -\phi\\ -\phi & 1\end{pmatrix}\begin{pmatrix}\underline{h}_{11} & \underline{h}_{12}\\ \underline{h}_{12} & \underline{h}_{22}\end{pmatrix}\left(\underline{\boldsymbol{\theta}}-\boldsymbol{\theta}^0\right)\\ &= \boldsymbol{\theta}^0+\xi\left(\xi'\underline{\mathrm{H}}\xi\right)^{-1}\xi'\underline{\mathbf{H}}\left(\underline{\theta}-\theta^0\right).\end{aligned}$$

Clearly, we have $p\lim_{T\to\infty}\left(\bar{\boldsymbol{\theta}}_T\right)=\boldsymbol{\theta}^0$, if $\underline{\boldsymbol{\theta}}=\boldsymbol{\theta}^0$, a sort of self-fulfillling belief.

Finally,

$$\bar{\theta}_{1,T}+\phi\bar{\theta}_{2,T}=\frac{\hat{\beta}_T\left(\phi^2a_{11}-2\phi a_{12}+a_{22}\right)+\frac{1}{T}\left(b_1a_{22}-b_2a_{12}\right)+\frac{1}{T}\phi\left(b_2a_{11}-b_1a_{12}\right)}{a_{11}\phi^2-2\phi a_{12}+a_{22}+T^{-1}\left[a_{11}a_{22}-a_{12}^2\right]}.$$

or

$$\bar{\theta}_{1,T}+\phi\bar{\theta}_{2,T}=\hat{\beta}_T+\frac{1}{T}\left[\frac{\left(b_1a_{22}-b_2a_{12}\right)+\phi\left(b_2a_{11}-b_1a_{12}\right)-\hat{\beta}_T\left[a_{11}a_{22}-a_{12}^2\right]}{a_{11}\phi^2-2\phi a_{12}+a_{22}}\right]+O(T^{-2})$$

Hence

$$p\lim_{T\to\infty}\left(\bar{\theta}_{1,T}+\phi\bar{\theta}_{2,T}\right)=p\lim_{T\to\infty}\left(\hat{\beta}_T\right)=\theta_1^0+\phi\theta_2^0.$$

Which is the only estimable function possible in a classical setting.

In the case where $\underline{\mathrm{h}}_{12}=0$, the above results simplify to

$$p\lim_{T\to\infty}\left(\bar{\theta}_{1,T}\right)=\theta_1^0+\frac{\phi^2\underline{\mathrm{h}}_{11}}{\underline{\mathrm{h}}_{11}\phi^2+\underline{\mathrm{h}}_{22}}\left(\underline{\theta}_1-\theta_1^0\right)-\frac{\phi\underline{\mathrm{h}}_{22}}{\underline{\mathrm{h}}_{11}\phi^2+\underline{\mathrm{h}}_{22}}\left(\underline{\theta}_2-\theta_2^0\right),$$

$$p\lim_{T\to\infty}\left(\bar{\theta}_{2,T}\right)=\theta_2^0-\frac{\phi\underline{\mathrm{h}}_{11}}{\underline{\mathrm{h}}_{11}\phi^2+\underline{\mathrm{h}}_{22}}\left(\underline{\theta}_1-\theta_1^0\right)+\frac{\underline{\mathrm{h}}_{22}}{\underline{\mathrm{h}}_{11}\phi^2+\underline{\mathrm{h}}_{22}}\left(\underline{\theta}_2-\theta_2^0\right)$$

which highlights the role of the prior precisions in the outcomes. In the case where the prior precisions are set to be the same across the parameters and $\underline{\mathrm{h}}_{12}=0$, (often done in practice) we have (10) and (11) above

$$p\lim_{T\to\infty}\left(\bar{\theta}_{1,T}\right)=\theta_1^0+\frac{\phi^2}{1+\phi^2}\left(\underline{\theta}_1-\theta_1^0\right)-\frac{\phi}{1+\phi^2}\left(\underline{\theta}_2-\theta_2^0\right),$$
$$p\lim_{T\to\infty}\left(\bar{\theta}_{2,T}\right)=\theta_2^0-\frac{\phi}{1+\phi^2}\left(\underline{\theta}_1-\theta_1^0\right)+\frac{\phi^2}{1+\phi^2}\left(\underline{\theta}_2-\theta_2^0\right),$$

and the limit of posterior means do not depend on the prior precisions, but do depend on the priors for the coefficients even asymptotically.

A2. Derivation of the posterior mean in the highly collinear case

In the highly collinear case we have

$$\begin{aligned}T^{-1}\mathbf{X}'\mathbf{X}=&\begin{pmatrix} s_T^2 & \phi s_T^2+T^{-1/2}\delta_T\ s_{1v,T}\\ \phi s_T^2+T^{-1/2}\delta_T\ s_{1v,T} & \phi^2 s_T^2+T^{-1}\delta_T^2 s_{vv,T}+2T^{-1/2}\phi\delta_T\ s_{1v,T}\end{pmatrix}\\ =&\ s_T^2\begin{pmatrix}1 & \phi\\ \phi & \phi^2\end{pmatrix}+\begin{pmatrix}0 & T^{-1/2}\delta_T\ s_{1v,T}\\ T^{-1/2}\delta_T\ s_{1v,T} & T^{-1}\delta_T^2 s_{vv,T}+2T^{-1/2}\phi\delta_T\ s_{1v,T}\end{pmatrix}.\end{aligned}$$

where

$$s_{1v,T}=T^{-1}\sum_{t=1}^{T}x_{1t}v_t,\ s_{vv,T}=T^{-1}\sum_{t=1}^{T}v_t^2.$$

Similarly,

$$T^{-1}\mathbf{X}'\mathbf{y}=\begin{pmatrix}T^{-1}\mathbf{x}_1'\mathbf{y}\\ T^{-1}\mathbf{x}_2'y\end{pmatrix}=\begin{pmatrix}s_T^2\hat{\beta}_T\\ T^{-1}\mathbf{y}'\left(\phi\mathbf{x}_1+\frac{\delta_T}{\sqrt{T}}\mathbf{v}\right)\end{pmatrix}=\begin{pmatrix}s_T^2\hat{\beta}_T\\ s_T^2\phi\hat{\beta}_T+\frac{\delta_T}{\sqrt{T}}T^{-1}\mathbf{y}'\mathbf{v}\end{pmatrix}$$

$$\sigma^{-2}T^{-1}\mathbf{X}'\mathbf{y}=\sigma^{-2}s_T^2\hat{\beta}_T\begin{pmatrix}1\\ \phi\end{pmatrix}+\begin{pmatrix}0\\ \frac{\delta_T}{\sigma^2\sqrt{T}}\left(T^{-1}\mathbf{y}'\mathbf{v}\right)\end{pmatrix},$$

where $s_{yv,T}=T^{-1}\sum_{t=1}^{T}y_tv_t$. Hence

$$\begin{aligned}\sigma^{-2}T^{-1}\mathbf{X}'\mathbf{X}+T^{-1}\underline{\mathrm{H}}=&\left(s_T^2/\sigma^2\right)\begin{pmatrix}1 & \phi\\ \phi & \phi^2\end{pmatrix}+\\ &T^{-1}\begin{pmatrix}\underline{\mathrm{h}}_{11} & \underline{\mathrm{h}}_{12}+\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\\ \underline{\mathrm{h}}_{12}+\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right) & \underline{\mathrm{h}}_{22}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)+2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\end{pmatrix}\end{aligned}$$

$$\sigma^{-2}T^{-1}\mathbf{X}'\mathbf{y}+T^{-1}\underline{\mathrm{H}}\ \underline{\theta}=\left(s_T^2/\sigma^2\right)\hat{\beta}_T\begin{pmatrix}1\\ \phi\end{pmatrix}+\begin{pmatrix}0\\ \frac{\delta_T}{\sigma^2\sqrt{T}}\left(T^{-1}\sum_{t=1}^T y_tv_t\right)\end{pmatrix}+T^{-1}\begin{pmatrix}b_1\\ b_2\end{pmatrix}$$

$$\sigma^{-2}T^{-1}\mathbf{X}'\mathbf{y}+T^{-1}\underline{\mathrm{H}}\ \underline{\theta}=\left(s_T^2/\sigma^2\right)\hat{\beta}_T\begin{pmatrix}1\\ \phi\end{pmatrix}+T^{-1}\begin{pmatrix}b_1\\ b_2+\frac{\delta_T}{\sigma^2}\left(T^{-1/2}\sum_{t=1}^T y_tv_t\right)\end{pmatrix}$$

$$\begin{aligned}T^{-1/2}\sum_{t=1}^T y_tv_t&=T^{-1/2}\sum_{t=1}^T v_t\left(\theta_1^0x_{1t}+\theta_2^0\left[\phi x_{1t}+\left(\delta_T/\sqrt{T}\right)v_t\right]+u_t\right)\\&=\theta_1^0\left(T^{-1/2}\sum_{t=1}^T v_tx_{1t}\right)+\theta_2^0\phi\left(T^{-1/2}\sum_{t=1}^T v_tx_{1t}\right)+\delta_T\theta_2^0\left(T^{-1}\sum_{t=1}^T v_t^2\right)+T^{-1/2}\sum_{t=1}^T v_tu_t\\&=\beta^0\left(T^{-1/2}\sum_{t=1}^T v_tx_{1t}\right)+\delta_T\theta_2^0\left(T^{-1}\sum_{t=1}^T v_t^2\right)+T^{-1/2}\sum_{t=1}^T v_tu_t.\end{aligned}$$

$$T^{-1/2}\sum_{t=1}^T y_tv_t=\delta_T\theta_2^0s_{vv,T}+\beta^0T^{-1/2}\sum_{t=1}^T v_t\left(x_{1t}+u_t\right)$$

$$s_T^2\hat{\beta}_T=T^{-1}\sum_{t=1}^T y_tx_{1t}=T^{-1}\sum_{t=1}^T x_{1t}\left(\theta_1^0x_{1t}+\theta_2^0\left[\phi x_{1t}+\left(\delta_T/\sqrt{T}\right)v_t\right]+u_t\right),$$

$$\hat{\beta}_T=\beta^0+\frac{\delta_T\theta_2^0}{\sqrt{T}}\left(\frac{s_{1v,T}}{s_T^2}\right)+\frac{s_{1u,T}}{s_T^2}. \tag{26}$$

$$\hat{\beta}_T\to_p\beta^0=\theta_1^0+\phi\theta_2^0.$$

Consider now the posterior means

$$\bar{\boldsymbol{\theta}}_T=\left[\begin{pmatrix}1&\phi\\ \phi&\phi^2\end{pmatrix}+T^{-1}\begin{pmatrix}a_{11}&a_{12}\\ a_{12}&a_{22}\end{pmatrix}\right]^{-1}\left[\hat{\beta}_T\begin{pmatrix}1\\ \phi\end{pmatrix}+T^{-1}\begin{pmatrix}b_1\\ b_2\end{pmatrix}\right],$$

where the a_{ij} and b_i are now given by

$$\mathbf{A}=\begin{pmatrix}a_{11}&a_{12}\\ a_{12}&a_{22}\end{pmatrix}=\left(\sigma^2/s_T^2\right)\begin{pmatrix}\underline{\mathrm{h}}_{11}&\underline{\mathrm{h}}_{12}+\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\\ \underline{\mathrm{h}}_{12}+\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)&\underline{\mathrm{h}}_{22}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)+2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\end{pmatrix},$$

$$\mathbf{b}=\begin{pmatrix}b_1\\ b_2\end{pmatrix}=\left(\sigma^2/s_T^2\right)\underline{\mathrm{H}}\ \underline{\theta}=\left(\sigma^2/s_T^2\right)\begin{pmatrix}\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\\ \underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2+\frac{\delta_T}{\sigma^2}\left(T^{-1/2}\sum_{t=1}^T y_tv_t\right)\end{pmatrix}$$

$$\bar{\boldsymbol{\theta}}_T=\begin{pmatrix}\frac{1}{a_{11}\phi^2-2\phi a_{12}+a_{22}+T^{-1}\left[a_{11}a_{22}-a_{12}^2\right]}\left(\hat{\beta}_T\left(a_{22}-\phi a_{12}\right)+\phi\left(\phi b_1-b_2\right)+T^{-1}\left(b_1a_{22}-b_2a_{12}\right)\right)\\ \frac{1}{a_{11}\phi^2-2\phi a_{12}+a_{22}+T^{-1}\left[a_{11}a_{22}-a_{12}^2\right]}\left(b_2-\phi b_1-\hat{\beta}_T\left(a_{12}-\phi a_{11}\right)+T^{-1}\left(b_2a_{11}-b_1a_{12}\right)\right)\end{pmatrix},$$

To evaluate this first consider the denominator of $\bar{\theta}_{1,T}$, where both numerator and denominator are multiplied by $\left(\sigma^2/s_T^2\right)^{-1}$

$$\left(\sigma^2/s_T^2\right)^{-1}\left[\hat{\beta}_T\left(a_{22}-\phi a_{12}\right)+\phi\left(\phi b_1-b_2\right)+T^{-1}\left(b_1 a_{22}-b_2 a_{12}\right)\right]$$
$$=\left[\beta^0+\frac{\delta_T\theta_2^0}{\sqrt{T}}\left(\frac{s_{1v,T}}{s_T^2}\right)+\frac{s_{1u,T}}{s_T^2}\right]\left[\underline{\mathrm{h}}_{22}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)+2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)-\phi\underline{\mathrm{h}}_{12}-\phi\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right]$$
$$+\phi^2\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)-\phi\left[\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2+\frac{\delta_T}{\sigma^2}\left[\delta_T\theta_2^0 s_{vv,T}+\beta^0 T^{-1/2}\sum_{t=1}^T v_t\left(x_{1t}+u_t\right)\right]\right]$$
$$+\left(\sigma^2/s_T^2\right)T^{-1}\left[\begin{array}{c}\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)\left[\underline{\mathrm{h}}_{22}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)+2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\right]\\-\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2+\frac{\delta_T}{\sigma^2}\left(T^{-1/2}\sum_{t=1}^T y_t v_t\right)\right)\left(\underline{\mathrm{h}}_{12}+\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right)\end{array}\right]$$

$$=\left[\beta^0+\frac{\delta_T\theta_2^0}{\sqrt{T}}\left(\frac{s_{1v,T}}{s_T^2}\right)+\frac{s_{1u,T}}{s_T^2}\right]\left[\underline{\mathrm{h}}_{22}-\phi\underline{\mathrm{h}}_{12}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)+\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\right]$$
$$+\phi^2\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)-\phi\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2\right)-\frac{\phi\delta_T}{\sigma^2}\left[\delta_T\theta_2^0 s_{vv,T}+\beta^0 T^{-1/2}\sum_{t=1}^T v_t\left(x_{1t}+u_t\right)\right]$$
$$+\left(\sigma^2/s_T^2\right)T^{-1}\left[\begin{array}{c}\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)\left[\underline{\mathrm{h}}_{22}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)\right]+2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)\\-\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2+\frac{\delta_T}{\sigma^2}\left(T^{-1/2}\sum_{t=1}^T y_t v_t\right)\right)\left(\underline{\mathrm{h}}_{12}+\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right)\end{array}\right]$$

$$=\left[\beta^0+\frac{\delta_T\theta_2^0}{\sqrt{T}}\left[\frac{s_{1v,T}}{s_T^2}\right]+\frac{s_{1u,T}}{s_T^2}\right]\left[\underline{\mathrm{h}}_{22}-\phi\underline{\mathrm{h}}_{12}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)\right]$$
$$+\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\frac{s_{1u,T}}{s_T^2}+\phi\delta_T^2\theta_2^0\left(s_{1v,T}/\sigma^2\right)\left[\frac{s_{1v,T}}{s_T^2}\right]$$
$$+\phi^2\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)-\phi\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2\right)$$
$$-\frac{\phi\delta_T}{\sigma^2}\delta\theta_2^0 s_{vv,T}-\frac{\phi\delta_T}{\sigma^2}\beta^0 T^{-1/2}\sum_{t=1}^T v_t\left(x_{1t}+u_t\right)+\beta^0\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)$$
$$+\left(\sigma^2/s_T^2\right)T^{-1}\left[\begin{array}{c}\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)\left[\underline{\mathrm{h}}_{22}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)\right]+2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)\\-\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2+\frac{\delta_T}{\sigma^2}\left(T^{-1/2}\sum_{t=1}^T y_t v_t\right)\right)\left(\underline{\mathrm{h}}_{12}+\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right)\end{array}\right]$$

$$=\left[\beta^0+\frac{\delta_T\theta_2^0}{\sqrt{T}}\left[\frac{s_{1v,T}}{s_T^2}\right]+\frac{s_{1u,T}}{s_T^2}\right]\left[\underline{\mathrm{h}}_{22}-\phi\underline{\mathrm{h}}_{12}+\delta_T^2\left(s_{vv,T}/\sigma^2\right)\right]+\phi\delta_T\left(\frac{T^{1/2}s_{1v,T}s_{1u,T}}{\sigma^2 s_T^2}\right)+\phi\delta_T^2\theta_2^0\left(\frac{s_{1v,T}^2}{\sigma^2 s_T^2}\right)$$
$$+\phi^2\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)-\phi\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2\right)-\frac{\phi\delta^2}{\sigma^2}\theta_2^0 s_{vv,T}-\frac{\beta\phi\delta}{\sigma^2}\left(T^{-1/2}\sum_{t=1}^T v_t u_t\right)$$
$$+\left(\sigma^2/s_T^2\right)T^{-1}\left[\begin{array}{c}\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)\left[\underline{\mathrm{h}}_{22}+\delta^2\left(s_{vv,T}/\sigma^2\right)\right]+2\phi\delta\left(T^{1/2}s_{1v,T}/\sigma^2\right)\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1+\underline{\mathrm{h}}_{12}\underline{\theta}_2\right)\\-\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1+\underline{\mathrm{h}}_{22}\underline{\theta}_2+\frac{\delta}{\sigma^2}\left(T^{-1/2}\sum_{t=1}^T y_t v_t\right)\right)\left(\underline{\mathrm{h}}_{12}+\delta\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right)\end{array}\right]$$

$$
\begin{aligned}
&= \left[\frac{\delta_T \theta_2^0}{\sqrt{T}} \left(\frac{s_{1v,T}}{s_T^2}\right) + \frac{s_{1u,T}}{s_T^2}\right] \left[\underline{\mathrm{h}}_{22} - \phi \underline{\mathrm{h}}_{12} + \delta_T^2 \left(s_{vv,T}/\sigma^2\right)\right] + \beta \left(\underline{\mathrm{h}}_{22} - \phi \underline{\mathrm{h}}_{12}\right) \\
&+ \phi \delta \left(\frac{T^{1/2} s_{1v,T} s_{1u,T}}{\sigma^2 s_T^2}\right) + \phi \delta_T^2 \theta_2^0 \left(\frac{s_{1v,T}^2}{\sigma^2 s_T^2}\right) - \frac{\phi \delta_T^2}{\sigma^2} \theta_2^0 s_{vv,T} + \delta_T^2 \beta \left(s_{vv,T}/\sigma^2\right) \\
&\phi^2 \left(\underline{\mathrm{h}}_{11} \underline{\theta}_1 + \underline{\mathrm{h}}_{12} \underline{\theta}_2\right) - \phi \left(\underline{\mathrm{h}}_{12} \underline{\theta}_1 + \underline{\mathrm{h}}_{22} \underline{\theta}_2\right) - \frac{\beta \phi \delta_T}{\sigma^2} \left(T^{-1/2} \sum_{t=1}^{T} v_t u_t\right) \\
&+ \left(\sigma^2 / s_T^2\right) T^{-1} \left[\begin{array}{c} \left(\underline{\mathrm{h}}_{11} \underline{\theta}_1 + \underline{\mathrm{h}}_{12} \underline{\theta}_2\right) \left[\underline{\mathrm{h}}_{22} + \delta_T^2 \left(s_{vv,T}/\sigma^2\right)\right] + 2\phi \delta_T \left(T^{1/2} s_{1v,T}/\sigma^2\right) \left(\underline{\mathrm{h}}_{11} \underline{\theta}_1 + \underline{\mathrm{h}}_{12} \underline{\theta}_2\right) \\ - \left(\underline{\mathrm{h}}_{12} \underline{\theta}_1 + \underline{\mathrm{h}}_{22} \underline{\theta}_2 + \frac{\delta_T}{\sigma^2} \left(T^{-1/2} \sum_{t=1}^{T} y_t v_t\right)\right) \left(\underline{\mathrm{h}}_{12} + \delta_T \ \left(T^{1/2} s_{1v,T}/\sigma^2\right)\right) \end{array}\right]
\end{aligned}
$$

$$
\begin{aligned}
&= \left[\frac{\delta_T \theta_2^0}{\sqrt{T}} \left[\frac{s_{1v,T}}{s_T^2}\right] + \frac{s_{1u,T}}{s_T^2}\right] \left[\underline{\mathrm{h}}_{22} - \phi \underline{\mathrm{h}}_{12} + \delta_T^2 \left(s_{vv,T}/\sigma^2\right)\right] \\
&+ \phi \delta_T \left(\frac{T^{1/2} s_{1v,T} s_{1u,T}}{\sigma^2 s_T^2}\right) + \phi \delta_T^2 \theta_2^0 \left(\frac{s_{1v,T}^2}{\sigma^2 s_T^2}\right) + \delta_T^2 \theta_1 \left(s_{vv,T}/\sigma^2\right) \\
&\phi^2 \left(\underline{\mathrm{h}}_{11} \underline{\theta}_1 + \underline{\mathrm{h}}_{12} \underline{\theta}_2\right) - \phi \left(\underline{\mathrm{h}}_{12} \underline{\theta}_1 + \underline{\mathrm{h}}_{22} \underline{\theta}_2\right) + \beta \left(\underline{\mathrm{h}}_{22} - \phi \underline{\mathrm{h}}_{12}\right) - \frac{\beta \phi \delta_T}{\sigma^2} \left(T^{-1/2} \sum_{t=1}^{T} v_t u_t\right) \\
&+ \left(\sigma^2 / s_T^2\right) T^{-1} \left[\begin{array}{c} \left(\underline{\mathrm{h}}_{11} \underline{\theta}_1 + \underline{\mathrm{h}}_{12} \underline{\theta}_2\right) \left[\underline{\mathrm{h}}_{22} + \delta_T^2 \left(s_{vv,T}/\sigma^2\right)\right] + 2\phi \delta_T \left(T^{1/2} s_{1v,T}/\sigma^2\right) \left(\underline{\mathrm{h}}_{11} \underline{\theta}_1 + \underline{\mathrm{h}}_{12} \underline{\theta}_2\right) \\ - \left(\underline{\mathrm{h}}_{12} \underline{\theta}_1 + \underline{\mathrm{h}}_{22} \underline{\theta}_2 + \frac{\delta_T}{\sigma^2} \left(T^{-1/2} \sum_{t=1}^{T} y_t v_t\right)\right) \left(\underline{\mathrm{h}}_{12} + \delta_T \ \left(T^{1/2} s_{1v,T}/\sigma^2\right)\right) \end{array}\right]
\end{aligned}
$$

When δ_T is bounded in T we have

$$
\begin{aligned}
\bar{\theta}_{1,T} = &-\frac{\beta \phi \delta_T}{\sigma^2 \left[\underline{\mathrm{h}}_{11} \phi^2 - 2\phi \underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \frac{\delta_T^2 s_{vv,T}}{\sigma^2}\right]} \left(T^{-1/2} \sum_{t=1}^{T} v_t u_t\right) + \\
&\frac{\phi^2 \left(\underline{\mathrm{h}}_{11} \underline{\theta}_1 + \underline{\mathrm{h}}_{12} \underline{\theta}_2\right) - \phi \left(\underline{\mathrm{h}}_{12} \underline{\theta}_1 + \underline{\mathrm{h}}_{22} \underline{\theta}_2\right) + \beta \left(\underline{\mathrm{h}}_{22} - \phi \underline{\mathrm{h}}_{12}\right)}{\underline{\mathrm{h}}_{11} \phi^2 - 2\phi \underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \frac{\delta_T^2 s_{vv,T}}{\sigma^2}} \\
&+ \frac{\delta_T^2 \theta_1 \left(s_{vv,T}/\sigma^2\right)}{\underline{\mathrm{h}}_{11} \phi^2 - 2\phi \underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \frac{\delta_T^2 s_{vv,T}}{\sigma^2}} + O_p\left(T^{-1/2}\right)
\end{aligned}
$$

Similarly, for the denominator we note that

$$
\begin{aligned}
&\left(\sigma^2/s_T^2\right)^{-1}\left\{a_{11}\phi^2 - 2\phi a_{12} + a_{22} + T^{-1}\left[a_{11}a_{22} - a_{12}^2\right]\right\} \\
&= \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\left[\underline{\mathrm{h}}_{12} + \delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right] + \underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right) + 2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right) \\
&+ T^{-1}\left(\sigma^2/s_T^2\right)\left[\underline{\mathrm{h}}_{11}\left[\underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right) + 2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\right] - \left[\underline{\mathrm{h}}_{12} + \delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right]^2\right] \\
&= \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} - 2\phi\delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right) + \underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right) + 2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right) \\
&+ T^{-1}\left(\sigma^2/s_T^2\right)\left[\underline{\mathrm{h}}_{11}\left[\underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right) + 2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\right] - \left[\underline{\mathrm{h}}_{12} + \delta_T\ \left(T^{1/2}s_{1v,T}/\sigma^2\right)\right]^2\right] \\
&= \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right) \\
&+ T^{-1}\left(\sigma^2/s_T^2\right)\left[\begin{array}{c}\underline{\mathrm{h}}_{11}\underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right)\underline{\mathrm{h}}_{11} + 2\phi\delta_T\left(T^{1/2}s_{1v,T}/\sigma^2\right)\underline{\mathrm{h}}_{11} \\ -\underline{\mathrm{h}}_{12}^2 - \delta_T^2 T\left(s_{1v,T}/\sigma^2\right)^2 - 2\delta_T\underline{\mathrm{h}}_{12}\left(T^{1/2}s_{1v,T}/\sigma^2\right)\end{array}\right] \\
&= \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right) - \delta_T^2\left(s_{1v,T}/\sigma^2\right)^2\left(\sigma^2/s_T^2\right) \\
&+ 2T^{-1/2}\phi\delta_T\left(s_{1v,T}/\sigma^2\right)\underline{\mathrm{h}}_{11}\left(\sigma^2/s_T^2\right) - 2\delta_T\underline{\mathrm{h}}_{12}\left(s_{1v,T}/\sigma^2\right)\left(\sigma^2/s_T^2\right) \\
&+ T^{-1}\left(\sigma^2/s_T^2\right)\left[\underline{\mathrm{h}}_{11}\underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right)\underline{\mathrm{h}}_{11} - \underline{\mathrm{h}}_{12}^2\right]
\end{aligned}
$$

Or

$$
\begin{aligned}
&\left(\sigma^2/s_T^2\right)^{-1}\left\{a_{11}\phi^2 - 2\phi a_{12} + a_{22} + T^{-1}\left[a_{11}a_{22} - a_{12}^2\right]\right\} \\
&= \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \delta_T^2\left[\frac{s_{vv,T}s_T^2 - s_{1v,T}^2}{\sigma^2 s_T^2}\right] \\
&+ 2T^{-1/2}\delta_T\left(s_{1v,T}/s_T^2\right)\left[\phi\underline{\mathrm{h}}_{11} - \underline{\mathrm{h}}_{12}\right] \\
&+ T^{-1}\left(\sigma^2/s_T^2\right)\left[\underline{\mathrm{h}}_{11}\underline{\mathrm{h}}_{22} + \delta_T^2\left(s_{vv,T}/\sigma^2\right)\underline{\mathrm{h}}_{11} - \underline{\mathrm{h}}_{12}^2\right]
\end{aligned}
$$

In the case where δ_T is bounded in T we obtain

$$
\begin{aligned}
&\left(\sigma^2/s_T^2\right)^{-1}\left\{a_{11}\phi^2 - 2\phi a_{12} + a_{22} + T^{-1}\left[a_{11}a_{22} - a_{12}^2\right]\right\} \\
&= \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \frac{\delta_T^2 s_{vv,T}}{\sigma^2} + O_p(T^{-1})
\end{aligned}
$$

But $s_{1v,T} = O_p(T^{-1/2})$, and $s_{vv,T} = \sigma_v^2 + O_p(T^{-1})$

$$
\begin{aligned}
\bar{\theta}_{1,T} &= \frac{\phi^2\left(\underline{\mathrm{h}}_{11}\underline{\theta}_1 + \underline{\mathrm{h}}_{12}\underline{\theta}_2\right) - \phi\left(\underline{\mathrm{h}}_{12}\underline{\theta}_1 + \underline{\mathrm{h}}_{22}\underline{\theta}_2\right) + \beta^0\left(\underline{\mathrm{h}}_{22} - \phi\underline{\mathrm{h}}_{12}\right)}{\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \left(\frac{\delta_T^2\sigma_v^2}{\sigma^2}\right)} \\
&+ \frac{\theta_1^0\left(\frac{\delta_T^2\sigma_v^2}{\sigma^2}\right)}{\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \left(\frac{\delta_T^2\sigma_v^2}{\sigma^2}\right)} \\
&+ \frac{-\beta^0\phi\sigma_v\sigma\delta_T}{\sigma^2\left[\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} + \left(\frac{\delta_T^2\sigma_v^2}{\sigma^2}\right)\right]}\left(T^{-1/2}\sum_{t=1}^{T}\frac{v_t u_t}{\sigma_v\sigma}\right) + O_p\left(T^{-1/2}\right).
\end{aligned}
$$

The above results can be simplified further by setting $\lambda_T^2 = \delta_T^2\sigma_v^2/\sigma^2$, and noting that $\beta^0 =$

$\theta_1^0 + \phi\theta_2^0$, $\underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22} = \psi'\underline{\mathbf{H}}\psi$, where $\boldsymbol{\psi} = (\phi, -1)'$. Specifically,

$$\bar{\theta}_{1,T} = \theta_1^0 + \frac{\phi\left(\underline{\mathrm{h}}_{11}\phi - \underline{\mathrm{h}}_{12}\right)\left(\underline{\theta}_1 - \theta_1^0\right)}{\lambda_T^2 + \boldsymbol{\psi}'\underline{\mathbf{H}}\boldsymbol{\psi}} - \frac{\phi\left(\underline{\mathrm{h}}_{22} - \phi\underline{\mathrm{h}}_{12}\right)\left(\underline{\theta}_2 - \theta_2^0\right)}{\lambda_T^2 + \boldsymbol{\psi}'\underline{\mathbf{H}}\boldsymbol{\psi}} - \left(\frac{\beta^0\phi\lambda_T}{\lambda_T^2 + \boldsymbol{\psi}'\underline{\mathbf{H}}\boldsymbol{\psi}}\right)\left(T^{-1/2}\sum_{t=1}^{T}\frac{v_t u_t}{\sigma_v\sigma}\right) + O_p\left(T^{-1/2}\right). \tag{27}$$

Thus as $T \to \infty$, in the highly collinear case where λ_T is bounded in T, the posterior mean, $\bar{\theta}_{1,T}$, converges in distribution to a normally distributed random variable given in subsection 3.1.

A3. Derivation of posterior precision in the highly collinear case

Starting with (17) we note that $\bar{\mathbf{V}}^{-1}$ can be written as

$$\bar{\mathbf{V}}^{-1} = \tilde{s}_T^2\begin{pmatrix} T & T\phi \\ T\phi & T\phi^2 \end{pmatrix} + \begin{pmatrix} \underline{\mathrm{h}}_{11} & \underline{\mathrm{h}}_{12} + \chi_T z_T \\ \underline{\mathrm{h}}_{12} + \chi_T z_T & \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T \end{pmatrix},$$

where

$$\tilde{s}_T^2 = s_T^2/\sigma^2,\ \lambda_T^2 = \delta_T^2\left(s_{vv,T}/\sigma^2\right),\ \chi_T = \frac{\delta_T\sigma_v\sigma_{x_1}}{\sigma^2},$$

$$z_T = \frac{T^{1/2}s_{1v,T}}{\sigma_{x_1}\sigma_v} = T^{-1/2}\sum_{t=1}^{T}\frac{x_{1t}v_t}{\sigma_{x_1}\sigma_v}.$$

Hence

$$\bar{\mathbf{V}}^{-1} = \begin{pmatrix} \underline{\mathrm{h}}_{11} + T\tilde{s}_T^2 & T\phi\tilde{s}_T^2 + \underline{\mathrm{h}}_{12} + \chi_T z_T \\ T\phi\tilde{s}_T^2 + \underline{\mathrm{h}}_{12} + \chi_T z_T & T\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T \end{pmatrix},$$

and the posterior precision of θ_1 is given by the inverse of the first element of $\bar{\mathbf{V}}$, which is given by

$$\begin{aligned}
\bar{h}_{11,T} &= \underline{\mathrm{h}}_{11} + T\tilde{s}_T^2 - \frac{\left(T\phi\tilde{s}_T^2 + \underline{\mathrm{h}}_{12} + \chi_T z_T\right)^2}{T\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T} \\
&= \frac{\left(\underline{\mathrm{h}}_{11} + T\tilde{s}_T^2\right)\left(T\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T\right) - \left(T\phi\tilde{s}_T^2 + \underline{\mathrm{h}}_{12} + \chi_T z_T\right)^2}{T\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T} \\
&= \frac{\begin{array}{c}\underline{\mathrm{h}}_{11}\left(T\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T\right) + T\tilde{s}_T^2\left(\underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T\right) \\ -\underline{\mathrm{h}}_{12}^2 - \chi_T^2 z_T^2 - 2\underline{\mathrm{h}}_{12}\chi_T z_T - 2T\phi\tilde{s}_T^2\left(\underline{\mathrm{h}}_{12} + \chi_T z_T\right)\end{array}}{T\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T} \\
&= \frac{\begin{array}{c}T\underline{\mathrm{h}}_{11}\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{11}\lambda_T^2 + 2\underline{\mathrm{h}}_{11}\chi_T\phi z_T + T\tilde{s}_T^2\underline{\mathrm{h}}_{22} + T\tilde{s}_T^2\lambda_T^2 \\ \underline{\mathrm{h}}_{11}\underline{\mathrm{h}}_{22} - \underline{\mathrm{h}}_{12}^2 - \chi_T^2 z_T^2 - 2\underline{\mathrm{h}}_{12}\chi_T z_T - 2T\phi\tilde{s}_T^2\underline{\mathrm{h}}_{12}\end{array}}{T\phi^2\tilde{s}_T^2 + \underline{\mathrm{h}}_{22} + \lambda_T^2 + 2\chi_T\phi z_T}.
\end{aligned}$$

Or

$$\bar{h}_{11,T} = \frac{\begin{array}{c}T\tilde{s}_T^2\left(\lambda_T^2 + \underline{\mathrm{h}}_{11}\phi^2 - 2\phi\underline{\mathrm{h}}_{12} + \underline{\mathrm{h}}_{22}\right) - \chi_T^2 z_T^2 + 2\chi_T\left(\underline{\mathrm{h}}_{11}\phi - \underline{\mathrm{h}}_{12}\right)z_T + \\ +\underline{\mathrm{h}}_{11}\lambda_T^2 + \underline{\mathrm{h}}_{11}\underline{\mathrm{h}}_{22} - \underline{\mathrm{h}}_{12}^2\end{array}}{T\phi^2\tilde{s}_T^2 + 2\chi_T\phi z_T + \underline{\mathrm{h}}_{22} + \lambda_T^2}$$

from which the expression in the text, (18), for the posterior precision of θ_1 follows.

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